

DECODING DISTRIBUTED TREE STRUCTURES

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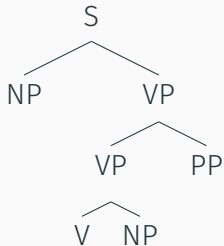
INTRODUCTION

- Natural language processing tasks benefit from syntactic information

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Directly

- Symbolic Tree Structures

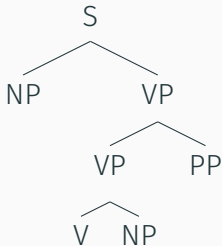


- Tree Kernels (Collins; 2001)

- Natural language processing tasks benefit from syntactic information

Directly

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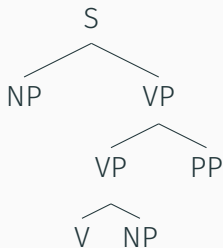
Indirectly

- Distributed Tree Structures

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Directly

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- Tree Kernels (Collins; 2001)

Indirectly

- Distributed Tree Structures

$$\longrightarrow \mathbf{t} = (0.0112, 0.212, \dots, 0.0081) \in \mathbb{R}^d$$

Distributed Trees (Zanzotto; 2012)

- Approximate tree kernels (Collins; 2001)

$$\langle \mathbf{t}_1, \mathbf{t}_2 \rangle \approx TK(T_1, T_2)$$

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$$\langle \mathbf{t}_1, \mathbf{t}_2 \rangle \approx TK(T_1, T_2)$$

- Faster to compute than tree kernels
- Can be used as input in any algorithm
 - Neural network
 - Support Vector Machines
 - ...

WHAT'S IN A DISTRIBUTED VECTORS?

Question

- How much information is stored in a distributed vector?
- In other words, can we decode the structured representation from a distributed vector?

Our Idea

- Traditional parsing:
 - CYK algorithm (and others)
- Use distributed vectors to “*guide*” the algorithm choices

CYK (Cocke, Younger, Kasami; 1967)

Given a sentence s of length n and a grammar G :

- builds a $n \times n$ table which contains the partial parses of the sentence

Grammar:

$S \rightarrow NP VP$

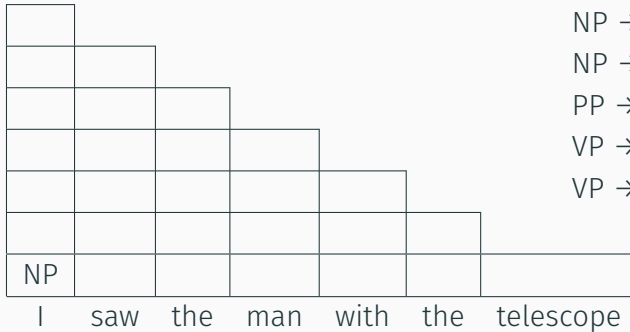
$NP \rightarrow DET N$

$NP \rightarrow NP PP$

$PP \rightarrow P NP$

$VP \rightarrow V NP$

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Grammar:

$S \rightarrow NP VP$

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$NP \rightarrow NP PP$

$PP \rightarrow P NP$

$VP \rightarrow V NP$

$VP \rightarrow VP PP$

NP	V						
I	saw	the	man	with	the	telescope	

NP	V	DET					
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NP	V	DET	N	P	DET		
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NP	V	DET	N	P	DET	N	
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We also store
backpointers to
record what rule
we choose



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		NP			NP	
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		NP			NP	
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S						
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		NP				
S						
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		NP				
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	VP					
		NP				
S						
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		NP			NP	
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	VP, VP					
		NP				
S						
	VP			PP		
		NP			NP	
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Again, we store
backpointers for
the two
possibilities

	VP, VP					
		NP				
S						
	VP			PP		
		NP			NP	
NP	V	DET	N	P	DET	N
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S						
	VP, VP					
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- Even in this small example there are two plausible interpretations
- In general there are (exponentially) many more!
- Usually parsers use probabilistic grammars to disambiguate
 - Each rule of the grammar has an inherent probability (which must be learned)

Idea

We show that a reference distributed vector of the correct parse is enough to eliminate ambiguity

(and thus reconstruct the original parse)

Ingredients:

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- Reference grammar G

Grammar:

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Ingredients:

- Reference grammar G
- Distributed vector \mathbf{t}

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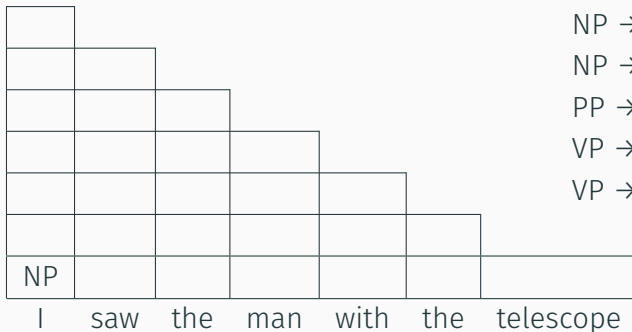
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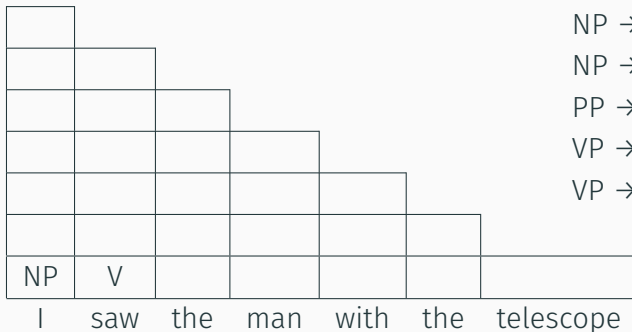
$$t \rightarrow \mathbf{t} = (0.011, 0.212, \dots, 0.008) \in \mathbb{R}^d$$

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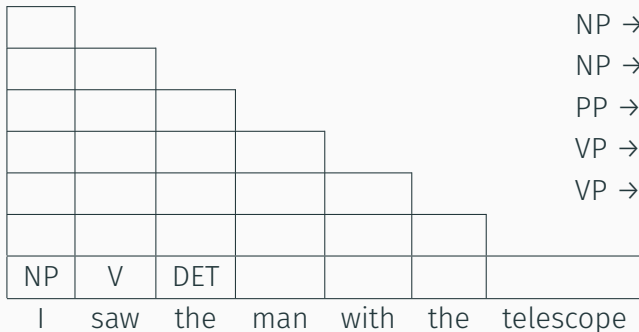
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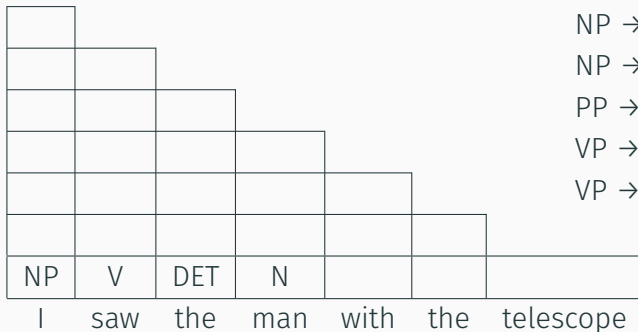
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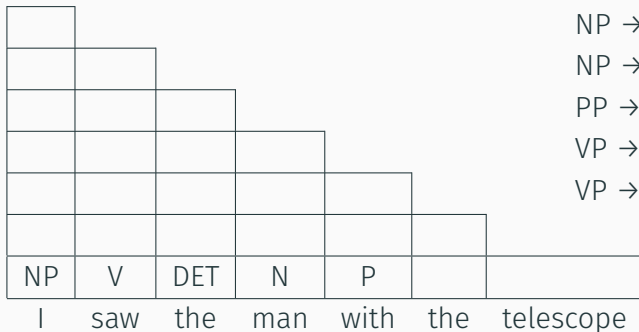
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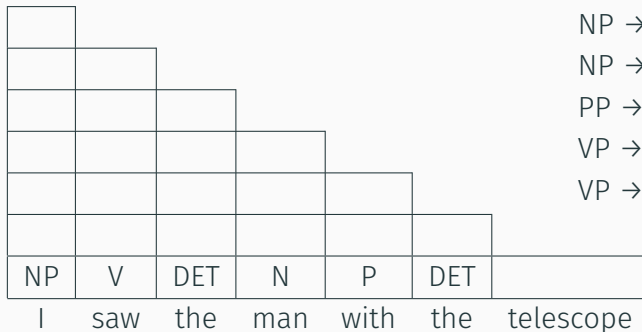
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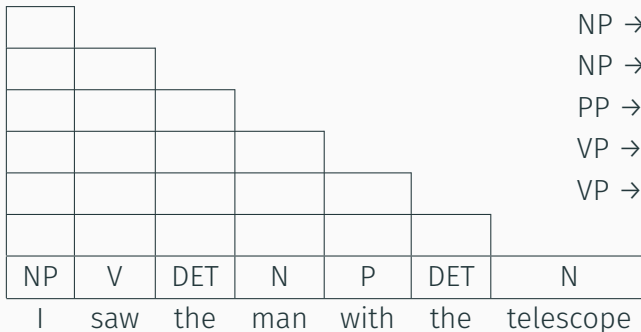
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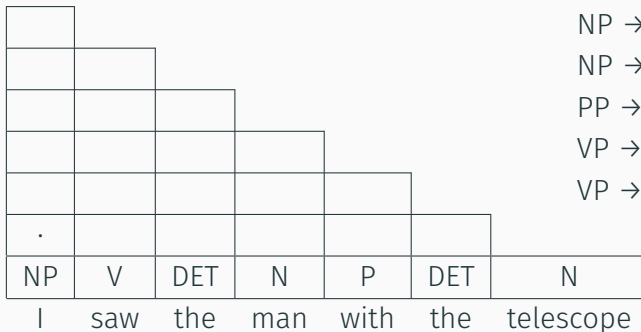
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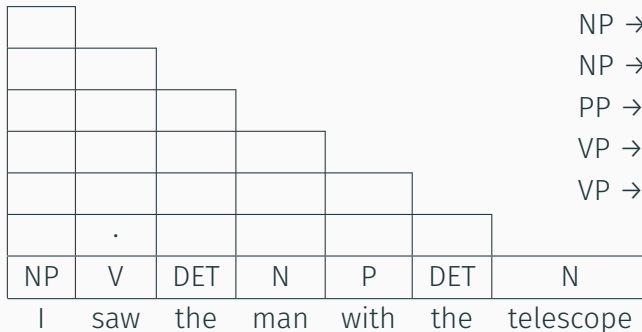
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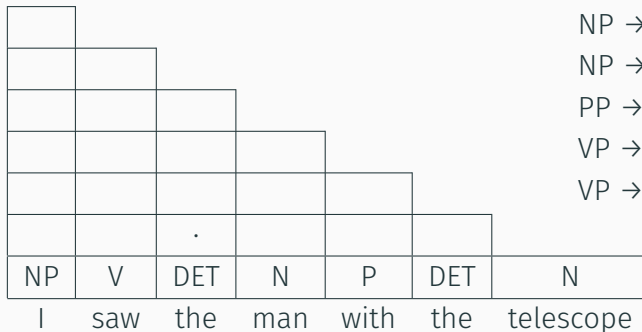
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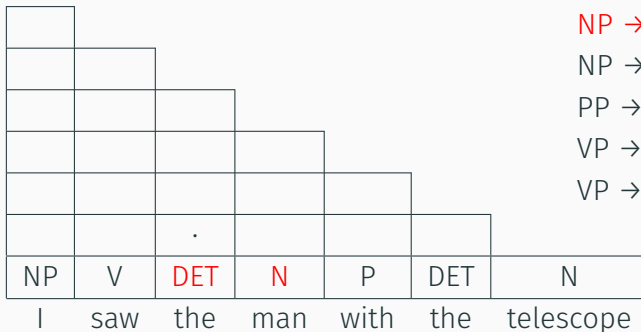
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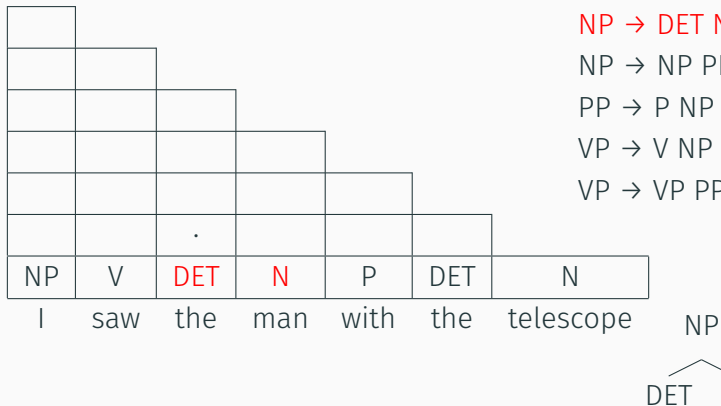
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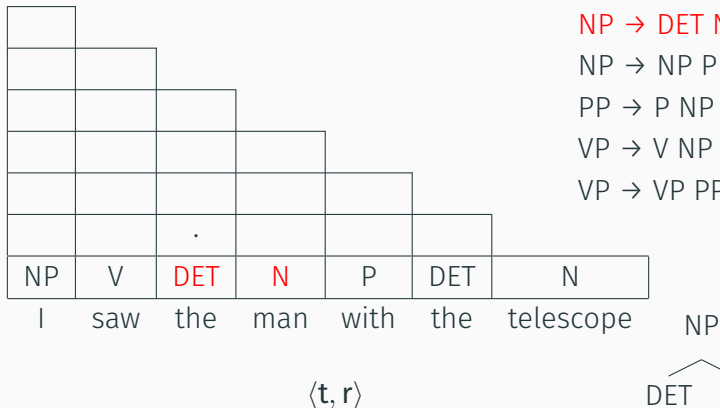
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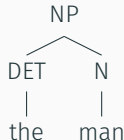


$$t \rightarrow \mathbf{t} = (0.011, 0.212, \dots, 0.008) \in \mathbb{R}^d \quad \mathbf{r} = (0.005, 0.043, \dots, 0.016)$$



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We store the full subtrees here!



Grammar:

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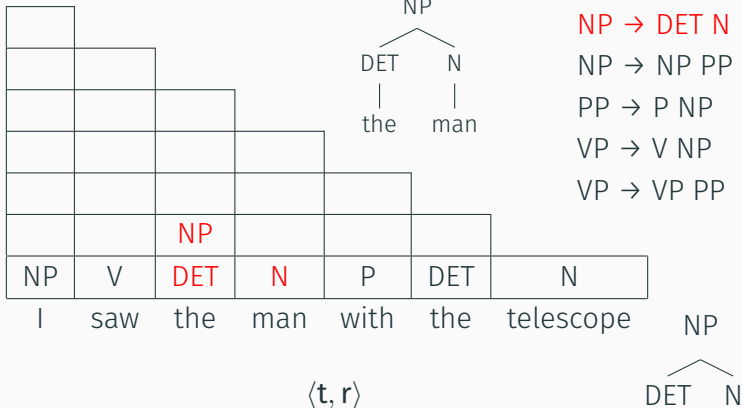
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$NP \rightarrow NP PP$

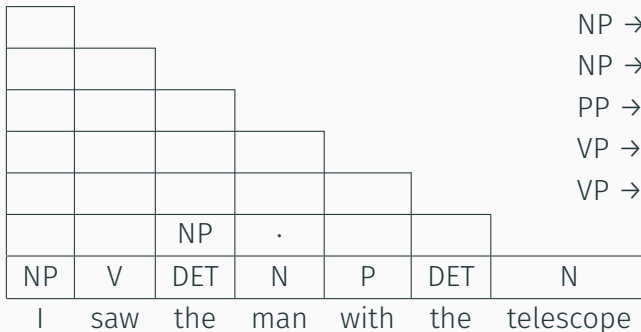
$PP \rightarrow P NP$

$VP \rightarrow V NP$

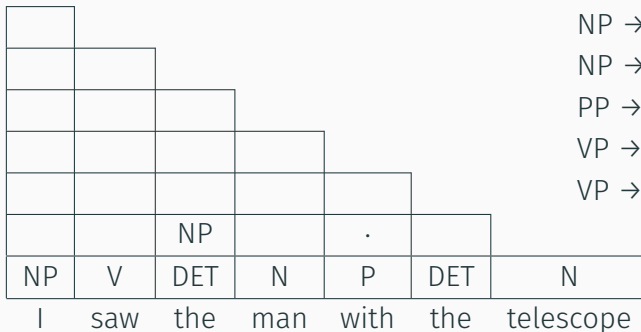
$VP \rightarrow VP PP$



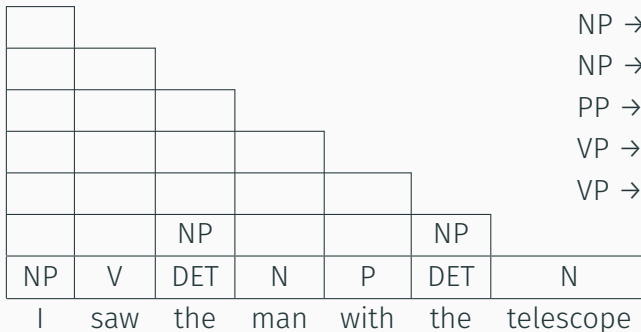
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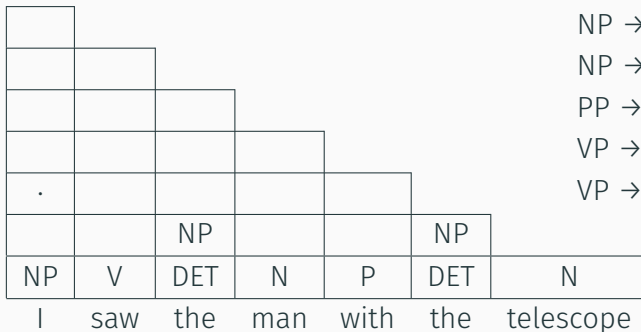
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	VP					
		NP			NP	
NP	V	DET	N	P	DET	N
I	saw	the	man	with	the	telescope

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	VP	.					
		NP			NP		
NP	V	DET	N	P	DET	N	
I	saw	the	man	with	the	telescope	

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$$t \rightarrow \mathbf{t} = (0.011, 0.212, \dots, 0.008) \in \mathbb{R}^d$$

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		NP				
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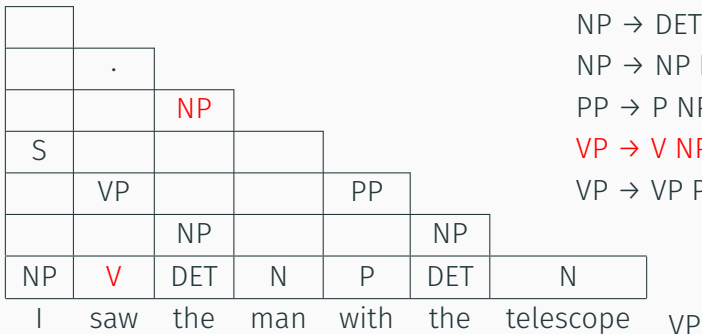
$$t \rightarrow \mathbf{t} = (0.011, 0.212, \dots, 0.008) \in \mathbb{R}^d$$

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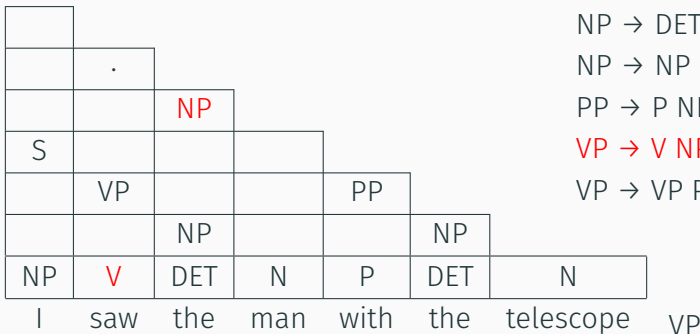
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$$\mathbf{r}_1 = (0.005, 0.043, \dots, 0.016)$$



$\langle \mathbf{t}, \mathbf{r}_1 \rangle$



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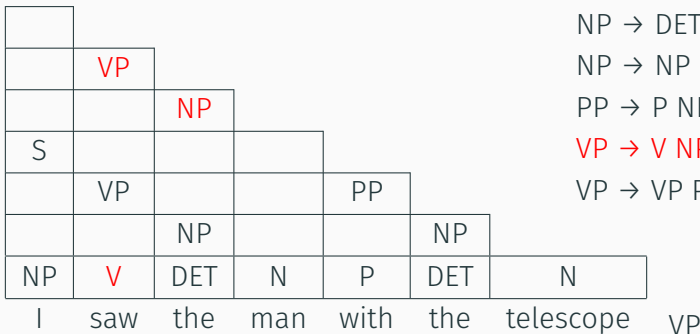
$PP \rightarrow P NP$

$VP \rightarrow V NP$

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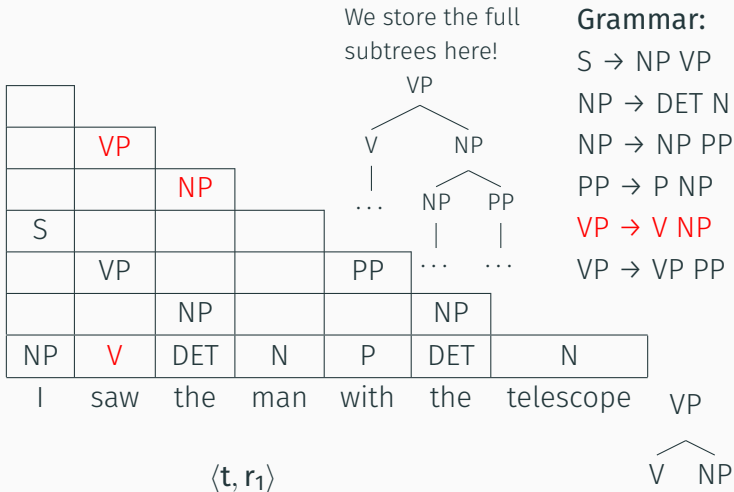
$VP \rightarrow VP PP$

$\langle \mathbf{t}, \mathbf{r}_1 \rangle$

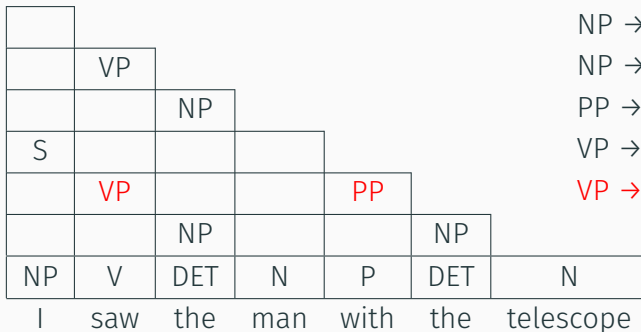


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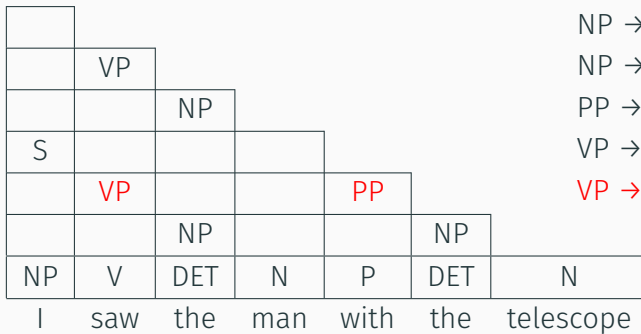
$$\mathbf{t} \rightarrow \mathbf{t} = (0.011, 0.212, \dots, 0.008) \in \mathbb{R}^d \quad \mathbf{r}_1 = (0.005, 0.043, \dots, 0.016)$$



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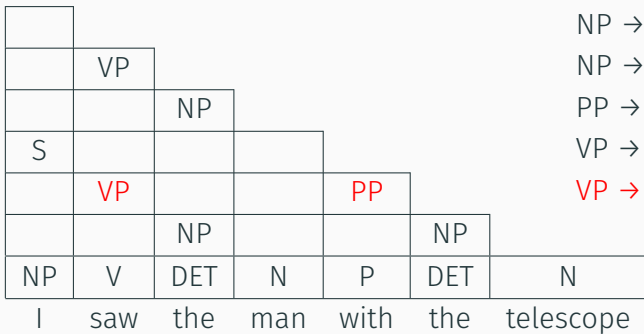
$VP \rightarrow V NP$

$VP \rightarrow VP PP$



$$\mathbf{t} \rightarrow \mathbf{t} = (0.011, 0.212, \dots, 0.008) \in \mathbb{R}^d$$

$$\mathbf{r}_2 = (0.001, 0.008, \dots, 0.024)$$



$\langle \mathbf{t}, \mathbf{r}_2 \rangle$



Grammar:

$S \rightarrow NP VP$

$NP \rightarrow DET N$

$NP \rightarrow NP PP$

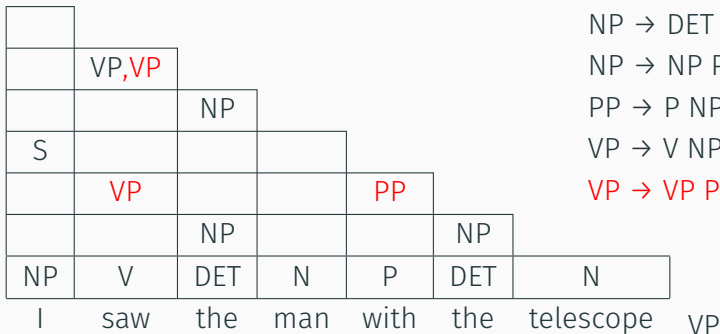
$PP \rightarrow P NP$

$VP \rightarrow V NP$

$VP \rightarrow VP PP$

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Grammar:

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$NP \rightarrow NP PP$

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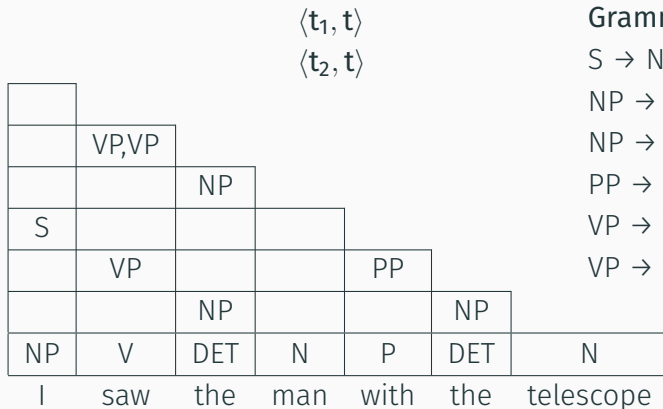
$VP \rightarrow VP PP$

$\langle \mathbf{t}, \mathbf{r}_2 \rangle$



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S							
	VP,VP						
		NP					
S							
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EXPERIMENTS AND RESULTS

Dataset

Wall Street Journal sections of PennTree Bank:

- Sections 1~23: Grammar extraction
- Section 24: testing

Experimental pipeline

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- Parse the dataset and binarize the trees

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- On test set (1346 sentences):
 - Compute the distributed vector \mathbf{t}
 - use \mathbf{t} to parse the sentence
 - compare the result with the correct tree

Parameters

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- d : Dimension of the vector representation

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- k : number of partial trees kept in each cell
 - we only report $k = 2$

Results

- Number of exactly reconstructed trees;
- (Labelled) precision, recall and f-measure;

1024	2048	4096	8192	16384
23.5%	52.32%	75.58%	87.5%	92.79%

Table 1: Percentage of exactly reconstructed sentence

	1024	2048	4096	8192	16384
<i>precision</i>	0.71	0.85	0.951	0.99	0.994
<i>recall</i>	0.477	0.78	0.929	0.967	0.976
<i>f-measure</i>	0.57	0.81	0.939	0.974	0.984

Table 2: Precision, recall and F-measure

SUMMARY AND FUTURE WORK

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Future work

- Expand the experimental setting:
 - from CNF to general grammars
- Use the reconstruction method on other distributed representations

QUESTIONS?